# M-230 Precision Linear Actuator 

## Non-Rotating Tip, Limit Switches, Stroke to 25 mm


$\mathrm{M}-230.10, \mathrm{M}-230.25$, high-resolution DC-Mike actuators, 10 and 25 mm travel range

Ordering Information<br>M-230.10<br>High-Resolution DC-Mike Linear Actuator, 10 mm, Limit Switches<br>M-230.10S<br>High-Resolution Stepper-Mike Linear Actuator, 10 mm, Limit Switches<br>M-230.25<br>High-Resolution DC-Mike Linear Actuator, 25 mm , Limit Switches<br>M-230.25S<br>High-Resolution Stepper-Mike<br>Linear Actuator, 25 mm, Limit Switches

M-230 are ultra-high-resolution linear actuators providing linear motion up to 25 mm with sub-micron resolution in a compact package. They consist of a micrometer with non-rotating tip driven by a 2-phase stepper motor or a closed-loop DC motor / gearhead combination with motor-shaft-mounted, high-resolution encoder.

## Non-Rotating Tip

Compared to conventional ro-tating-tip micrometer drives, the non-rotating-tip design offers several advantages:

## Application Examples

- Fiber positioning
- Metrology
- Photonics packaging
- Quality assurance testing
- Testing equipment
tomation applications with high precision.


## Integrated Line Drivers

All actuators include an integral 0.5 m cable with $15-\mathrm{pin}$ sub-D connector and come with a 3 m extension cable. On the DC servo versions, the connector features integrated line drivers for cable lengths up to 10 meters between actuator and controller.

## High-Load Versions

For higher loads and travel ranges refer to the M-235 (see p. 1-50) and M-238 (see p. 1-52).

A screw-in ball tip and a flat tip are included.


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M-230. Cable length: 500 mm , 15-pin sub-D connector with integrated
line drivers (DC motor models). Dimensions in mm

| Technical Data |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Model | M-230.10 | M-230.25 | M-230.10S | M-230.25S | Units |
| Active axes | X | X | X | X |  |
| Motion and positioning |  |  |  |  |  |
| Travel range | 10 | 25 | 10 | 25 | mm |
| Integrated sensor | Rotary encoder | Rotary encoder |  |  |  |
| Sensor resolution | 2,048 | 2,048 |  |  | Cts./rev. |
| Design resolution | 0.0046 | 0.0046 | 0.037 | 0.037 | $\mu \mathrm{m}$ |
| Min. incremental motion | 0.05 | 0.05 | 0.05 | 0.05 | $\mu \mathrm{m}$ |
| Backlash | 2 | 2 | 2 | 2 | $\mu \mathrm{m}$ |
| Unidirectional repeatability | 0.1 | 0.1 | 0.1 | 0.1 | $\mu \mathrm{m}$ |
| Max. velocity | 0.8 | 0.8 | 1.5 | 1.5 | $\mathrm{mm} / \mathrm{s}$ |
| Reference switch repeatability | 1 | 1 | 1 | 1 | $\mu \mathrm{m}$ |
| Mechanical properties |  |  |  |  |  |
| Spindle | Leadscrew | Leadscrew | Leadscrew | Leadscrew |  |
| Spindle pitch | 0.4 | 0.4 | 0.4 | 0.4 | mm |
| Gear ratio | 42.92063:1 | 42.92063:1 | 28.44444:1 | 28.44444:1 |  |
| Motor resolution** |  |  | 384** | 384** | steps/rev. |
| Max. push/pull force | 70 | 70 | 45* | 45* | N |
| Max. lateral force | 30 | 20 | 30 | 20 | N |
| Drive properties |  |  |  |  |  |
| Motor type | DC-motor, gearhead | DC-motor, gearhead | 2-phase stepper motor** | 2-phase stepper motor** |  |
| Operating voltage | 0 to $\pm 12$ | 0 to $\pm 12$ | 24 | 24 | V |
| Electrical power | 2 | 2 |  |  | W |
| Limit and reference switches | Hall-effect | Hall-effect | Hall-effect | Hall-effect |  |
| Miscellaneous |  |  |  |  |  |
| Operating temperature range | -20 to +65 | -20 to +65 | -20 to +65 | -20 to +65 | ${ }^{\circ} \mathrm{C}$ |
| Material | AI (anodized), steel | Al (anodized), steel | Al (anodized), steel | Al (anodized), steel |  |
| Mass | 0.3 | 0.35 | 0.3 | 0.35 | kg |
| Cable length | 0.5 | 0.5 | 0.5 | 0.5 | m |
| Connector | 15-pin sub-D connector | 15-pin sub-D connector | 15-pin sub-D connector | 15-pin sub-D connector |  |
| Recommended controller/driver | C-863 single-axis C-843 PCI board, for up to 4 axes | C-863 single-axis (p. 4-114) C-843 PCI board, for up to 4 axes (p. 4-120) | C-663 single-axis | C-663 single-axis (p. 4-112) |  |

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Nanometrology

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*at velocities of up to $1 \mathrm{~mm} / \mathrm{s}$
**2-phase stepper motor, 24 V chopper voltage, max. $0.25 \mathrm{~A} / \mathrm{phase}, 24$ full steps/rev., motor resolution with C-663 stepper motor controller

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